



COM-1518SOFT HIGH-SPEED DIRECT-SEQUENCE SPREAD- SPECTRUM DEMODULATOR VHDL SOURCE CODE / IP CORE

Overview

The COM-1518SOFT is a digital direct-sequence spread-spectrum demodulator written in VHDL, for intermediate frequency or baseband input signals. It is designed to be embodied within a single low-cost FPGA such as the Xilinx Spartan-6 LX45.

The entire **VHDL source code** is provided.

Key features and performance:

- Direct-Sequence Spread-Spectrum (DSSS) demodulation
- Continuous mode operation (i.e. Burst mode is not supported)
- Maximum processing gain: 33 dB
Spreading factor: 3 to 2047
- Code period can be (significantly) longer than symbol period:
Maximal code period: 65535
- Maximum chip rate: 50% of processing clock frequency.
 - 78 Mchips/s Xilinx Spartan-6 -2
 - 99 Mchips/s Xilinx Kintex-7 -2
- Parallel code search for fast code acquisition. The number of parallel search circuits instantiated within can be selected by the user prior to synthesis.
- False code lock prevention.
- Accurate time of arrival pulse generated once per code period (can be used for round-trip delay measurement for example).
- Built-in Bit Error Rate measurement.

Target Hardware

The code is written in generic VHDL so that it can be ported to a variety of FPGAs. The code was developed and tested on a Xilinx Spartan-6 FPGA.

It can be easily ported to any Xilinx Kintex7, Virtex-6, Spartan-6, Virtex-5 FPGAs and other FPGAs.

Device Utilization

Device: Xilinx Spartan-6 XC6SLX45-2

	30 parallel code acquisition circuits	% utilization
Flip Flops	9221	16%
LUTs	9414	34%
RAMB16BWERs	5	4%
DSP48A1s	20	34%
GCLKs	1	6%
DCMs/PLLs	0	0%

Device: Xilinx Kintex-7 XC7K70T-2

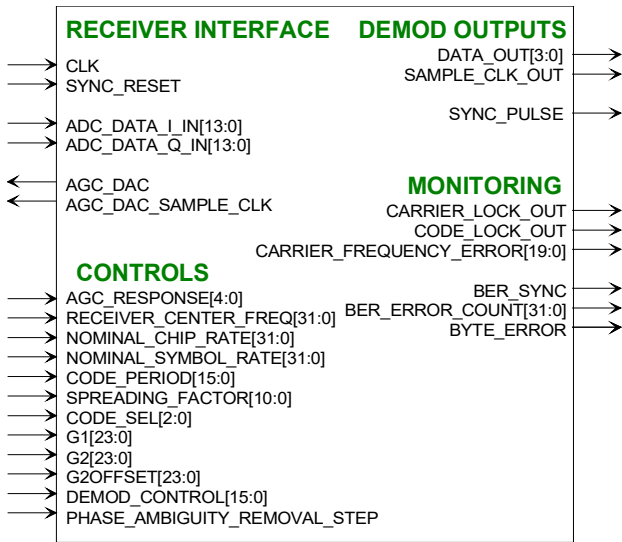
	30 parallel code acquisition circuits	% utilization
Flip Flops	8999	10%
LUTs	12195	29%
RAMB16BWERs	4	2%
DSP48E1s	20	8%
GCLKs	1	6%
DCMs/PLLs	0	0%

Clock speed

This design uses a single global clock, namely the ADC sampling clock. Typical maximum clock frequencies for various FPGA families are listed below:

Device family	f_{clk_rx}	Max. chip rate
Xilinx Kintex 7 -2	198 MHz	99 Mchips/s
Xilinx Virtex-6 -2	156 MHz	78 Mchips/s
Xilinx Spartan-6 -3	177 MHz	88 Mchips/s

Interfaces



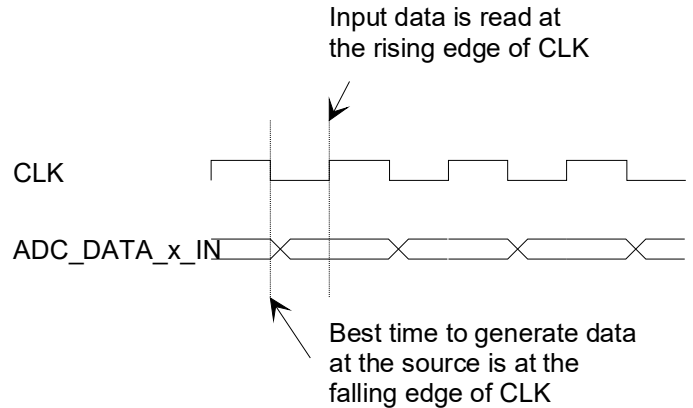
This component's interface comprises four distinct groups:

- the receiver interface typically connects to one (IF) or two (baseband) analog-to-digital converters (ADC). Use both I and Q inputs in the case of near-zero center frequency signal. Use the I input only in the case of IF input signal, while the Q input is set to zero.

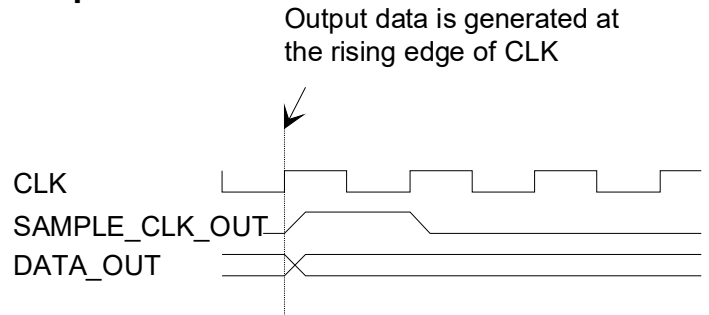
The entire component operates with a single clock CLK, typically the ADC sampling clock.

- The demodulator output consists of 4-bit soft-quantized output. The most significant bit DATA_OUT(3) represents the demodulated bit, while the remaining bits DATA_OUT(2:0) rate its quality.
- Controls can be changed at any time. In most cases, the component should be reset with a SYNC_RESET pulse after a configuration change.
- Monitoring

Input



Output



Monitoring and Control

Configuration

The key configuration parameters are brought to the interface so that the user can change them dynamically at run-time. Other, more arcane, parameters are fixed at the time of VHDL synthesis.

Pre-synthesis configuration parameters

The following configuration parameters are set as constants prior to synthesis

Configuration parameters in DSSS DEMOD2	Description
Number of parallel code acquisition circuits	<p>NACQ</p> <p>The larger this number, the faster the code acquisition time. The FPGA occupancy increases significantly as well.</p> <p>Limitation: NACQ must be selected to be less than half the spreading factor.</p>
Non-coherent Integration and Dump (I&D) period	<p>N_NCID</p> <p>Number of successive coherent I&D results accumulated non-coherently (power-wise) to improve the SNR before making a detection decision.</p> <p>Trade-off acquisition speed versus acquisition SNR threshold.</p>

Run-time configuration parameters

The user can set and modify the following controls at run-time. All controls are synchronous with the user-supplied global CLK. Most configuration changes should be followed by a SYNC_RESET pulse.

The FPGA processing clock equals the ADC sampling clock: f_{clk_rx}

Parameters	Configuration
AGC response time	<p>Users can to optimize AGC response time while avoiding instabilities (depends on external factors such as gain signal filtering at the RF front-end and chip rate). The AGC_DAC gain control signal is updated as follows</p> <p>0 = every chip, 1 = every 2 input chips, 2 = every 4 input chips, 3 = every 8 input chips, etc.... 10 = every 1000 input chips. Valid range 0 to 14.</p> <p>AGC_RESPONSE(4:0)</p>
Nominal Center frequency (f_{IF})	<p>The nominal center frequency can be null (in the case of a baseband input signal) or non-zero in the case of an IF input signal. If the IF center frequency is sufficiently greater than the modulation bandwidth (chip rate), the Q input can be ignored and force to zero, thus saving an ADC.</p> <p>This field can also be used for fine frequency corrections, for example to correct clock drifts.</p> <p>32-bit signed integer (2's complement representation) expressed as $f_{IF} * 2^{32} / f_{clk_rx}$</p> <p>RECEIVER_CENTER_FREQ(31:0)</p>
Chip rate ($f_{chip\ rate}$)	<p>32-bit integer expressed as $f_{chip\ rate} * 2^{32} / f_{clk_rx}$.</p> <p>The maximum practical chip rate is $f_{clk_rx} / 2$.</p> <p>Example for a 150 MHz f_{clk_rx}: 60 Mchips/s: 0x66666666</p> <p>The maximum allowed error between transmitted and received chip rate is +/- 100ppm.</p> <p>NOMINAL_CHIP_RATE(31:0)</p>

Code period	In chips. Valid range 3 – 65535 Can be less than the natural length of the selected code. In which case, the code is truncated. CODE_PERIOD(31:0)
Code selection	1 = Gold code 2 = Maximal length sequence 3 = Barker code (lengths 11 or 13 only) 4 = GPS C/A codes (use G2 as GPS PRN number) CODE_SEL(2:0)
Gold sequence / Maximal Length Sequence generator polynomial G1	24-bit. Describes the taps in the linear feedback shift register 1: Bit 0 is the leftmost tap (2^0 in the polynomial). The largest non-zero bit is the polynomial order n. n determines the code period $2^n - 1$. Example: G1 = $1 + x + x^4 + x^5 + x^6$ is represented as 0x000039 This field is used only if Gold code or Maximal length sequences are selected. G1(23:0)
Gold code generator polynomial G2	24-bit. Describes the taps in the linear feedback shift register 2: Same format as G1 above. This field is used only if Gold codes are selected. G2(23:0)
Gold code G1/G2 phase offset	A Gold code is generated by adding two maximal length sequences (as defined by their generator polynomials G1 and G2). A set of orthogonal Gold codes can be created by changing the phase offset between the two maximal length sequences. G2OFFSET(23:0)
GPS satellite ID	GPS signals from different satellites are designated by a PRN signal number in the range 1 – 37. This field is used only if GPS C/A codes are selected. G2(5:0)
Symbol rate $f_{\text{symbol_rate}}$	The symbol rate can be set independently of the spreading code period as $f_{\text{symbol_rate}} * 2^{32} / f_{\text{clk_tx}}$ Limitation: the symbol rate must be higher than chip rate / 2047. NOMINAL_SYMBOL_RATE(31:0)

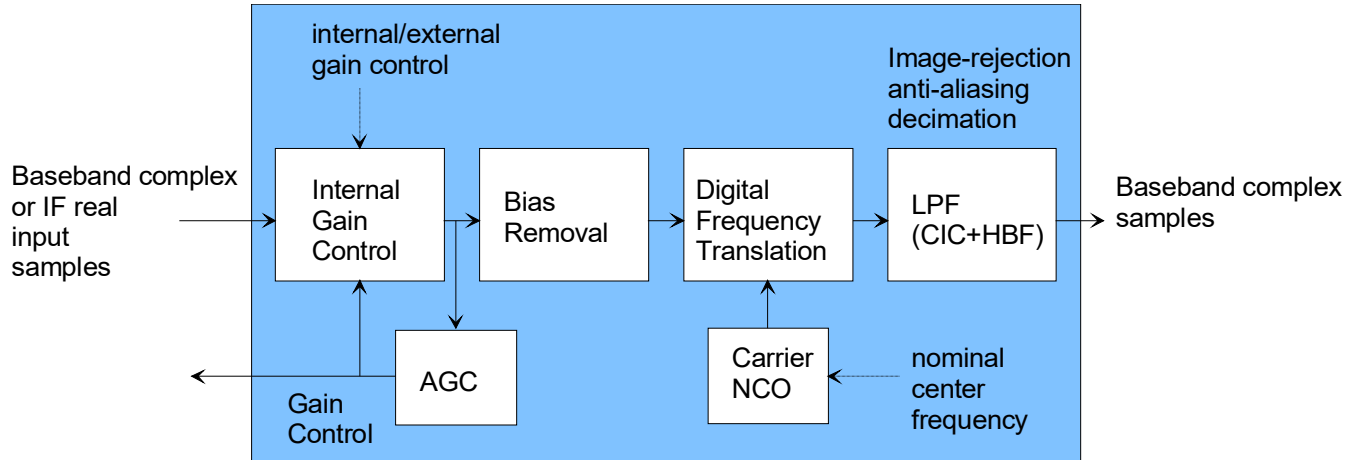
Spreading factor (Processing gain)	Approximate (i.e truncated) ratio of chip rate / symbol rate Range: 3 – 2047 Note: to effectively achieve this processing gain, the code period must be longer than one symbol duration. SPREADING_FACTOR(10:0)
Spectrum inversion	Invert Q bit. (Inverts the modulated spectrum only, not the subsequent frequency translation) 0 = off 1 = on DEMOM_CONTROL(0)
BPSK / QPSK decoding	Note: the modulation symbol transitions are not necessarily aligned with the chip transitions. 0 = BPSK 1 = QPSK DEMOM_CONTROL(1)
Carrier frequency loop gain	00 = nominal 01 = 2x loop gain 10 = 4x loop gain 11 = 8x loop gain DEMOM_CONTROL(3:2)
AFC enable	The automatic frequency control circuit extends the frequency acquisition over +/- 10% of the symbol rate. When disabled, the receiver only means of carrier acquisition is the carrier frequency tracking loop which is inherently limited to approximately 1% of the symbol rate. The AFC should only be active during acquisition as it interferes with the Costas Loop operation. 00 = automatic AFC selection. 01 = force AFC disabled. Carrier tracking loop only 10 = force AFC enabled. 11 = reserved (test). DEMOM_CONTROL(5:4)
Internal vs external AGC	The code can act as a level sensor for an external gain control actuator (for example RF or IF receiver gain control) to prevent saturation at the external A/D converter. If so, configure as “external” AGC. Otherwise, an internal AGC will prevent saturation from occurring within the FPGA. 0 = internal 1 = external DEMOM_CONTROL(6)

Phase ambiguity removal	The built-in PSK demodulator exhibits an inherent phase ambiguity (modulo 180 deg for BPSK, 90 deg for QPSK). Subsequent circuits such as FEC decoders can detect when the carrier tracking loop is locked onto the wrong carrier phase. By generating a 1 CLK-wide pulse, this demodulator will jump 180 deg(BPSK) or 90 deg (QPSK) to the next modulo. PHASE AMBIGUITY REMOVAL STEP
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Monitoring

Carrier lock	Carrier tracking loop status, based on the measured RMS phase error. May wrongly indicate lock when no input signal and no input noise is present. CARRIER LOCK OUT
Code lock	CODE LOCK OUT
Carrier frequency error	Measured frequency error relative to the nominal center frequency. 20-bit signed integer (2's complement representation) expressed as $f_{\text{error}} * 2^{20} / f_{\text{symbol_rate}}$ CARRIER FREQUENCY ERROR(19:0)
Bit error rate	Monitors the BER (number of bit errors over 1,000,000 received bits) when the modulator is sending a PRBS-11 test sequence. Valid only when BER analyzer is synchronized. BER ERROR COUNT(31:0)
BER analyzer synchronized	'1' when synchronized with the received PRBS-11 test sequence. BER SYNC
Byte error	One pulse for each byte error. Helpful in visualizing the bit error distribution (random? Burst?) with an oscilloscope. BYTE ERROR

Block Diagram: Receiver1



The ADC samples are first processed in the *RECEIVER1.vhd* component as illustrated above.

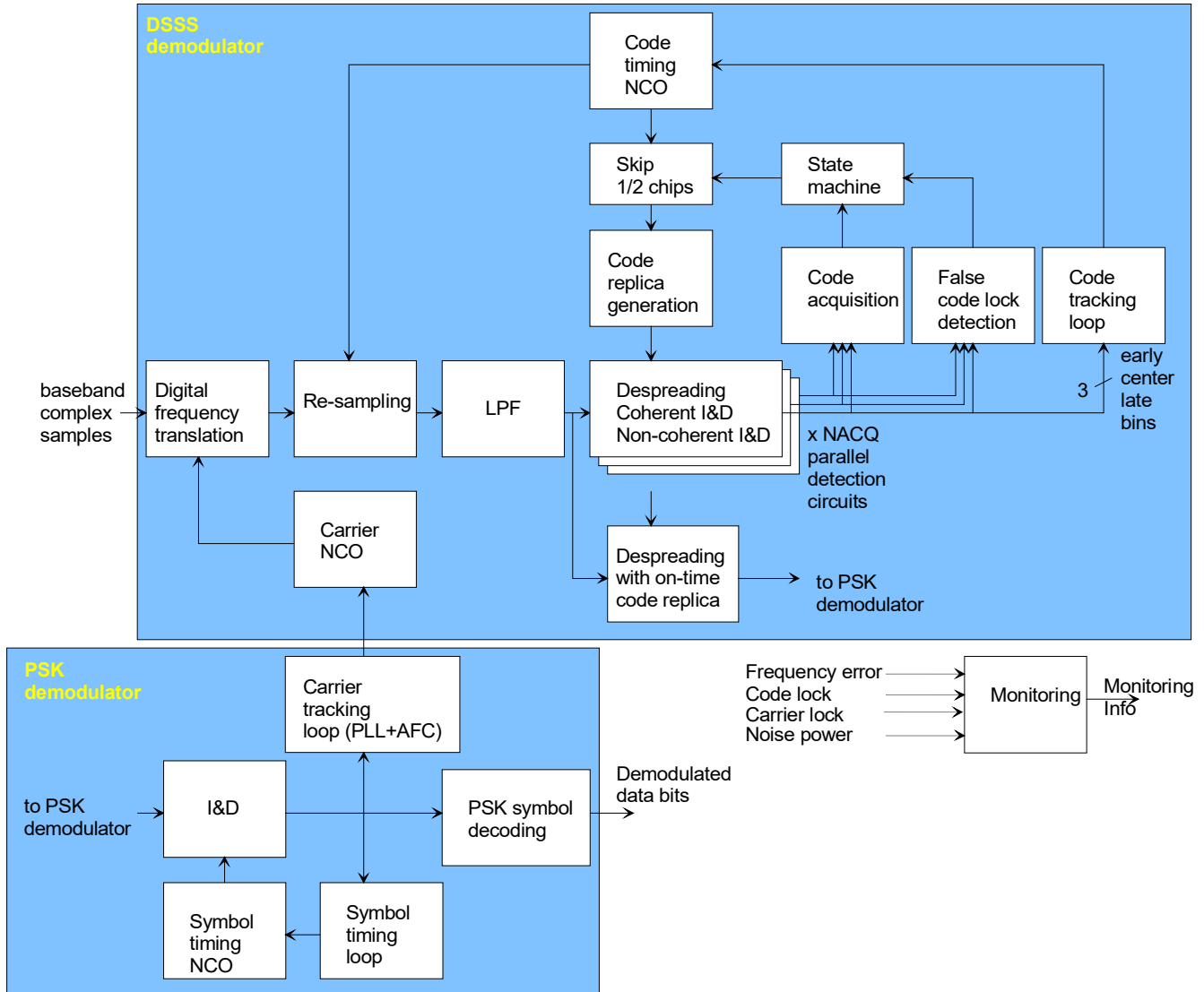
The AGC detects saturation or near saturation and adjust the gain control signal accordingly. This gain control is sent to either the internal or external gain control stage as per the configuration. The reaction time of the AGC loop is controlled by the `AGC_RESPONSE` parameter.

After DC bias removal, the real (IF) or complex (near baseband) input samples are frequency translated to baseband, as per the `RECEIVER_CENTER_FREQ` parameter.

The resulting baseband signal undergoes up to two types of low-pass filtering (CIC decimation and Half-Band filter), depending on the modulation bandwidth (or more specifically, depending on the ratio of the sampling rate over the chip rate). These low-pass filters are used for (a) image-rejection, in the case of IF inputs, (b) anti-aliasing prior to decimation.

Resulting baseband complex samples are further sent to the *DSSS_DEMOD2.vhd* component, as illustrated below.

Block Diagram: DSSS_Demod2



The *DSSS_DEMOD2.vhd* component conceptually comprises two distinct and mostly independent sections: (a) a spread-spectrum receiver (code acquisition and despreading) followed by (b) a regular PSK demodulator. Architecturally, this means that the PSK modulation could be replaced with other modulation types without much effort.

NACQ parallel code acquisition circuits are used for faster code acquisition. Each circuit consists of a code replica delay, despreading, coherent integration and dump (I&D) over a period of approximately half a symbol period, and non-coherent (i.e. power) I&D over a period of approximately $N_{NCID}/2$ symbols.

During the code acquisition phase, these parallel circuits are used to search **NACQ** code epochs spaced $1/2$ a chip apart.

During the code tracking phase, three parallel circuits are used to compare the early/on-time/late code epochs for code tracking. The remaining parallel circuits are used to search for false code lock (a consistently better code epoch).

Software Licensing

The COM-1518SOFT is supplied under the following key licensing terms:

1. A nonexclusive, nontransferable license to use the VHDL source code internally, and
2. An unlimited, royalty-free, nonexclusive transferable license to make and use products incorporating the licensed materials, solely in bitstream format, on a worldwide basis.

The complete VHDL/IP Software License Agreement can be downloaded from <http://www.comblock.com/download/softwarelicense.pdf>

Configuration Management

The current software revision is 1.

Directory	Contents
/doc	Specifications, user manual, implementation documents
/src	.vhd source code, .ucf constraint files One component per file.
/sim	Test benches, Matlab .m signal generation
/bin	n/a

Key files:

Xilinx ISE project file: com-1518_ISE141.xise

VHDL development environment

The VHDL software was developed using the following development environment:

- (a) Xilinx ISE 14.1 with XST as synthesis tool
- (b) Xilinx ISE Isim as VHDL simulation tool

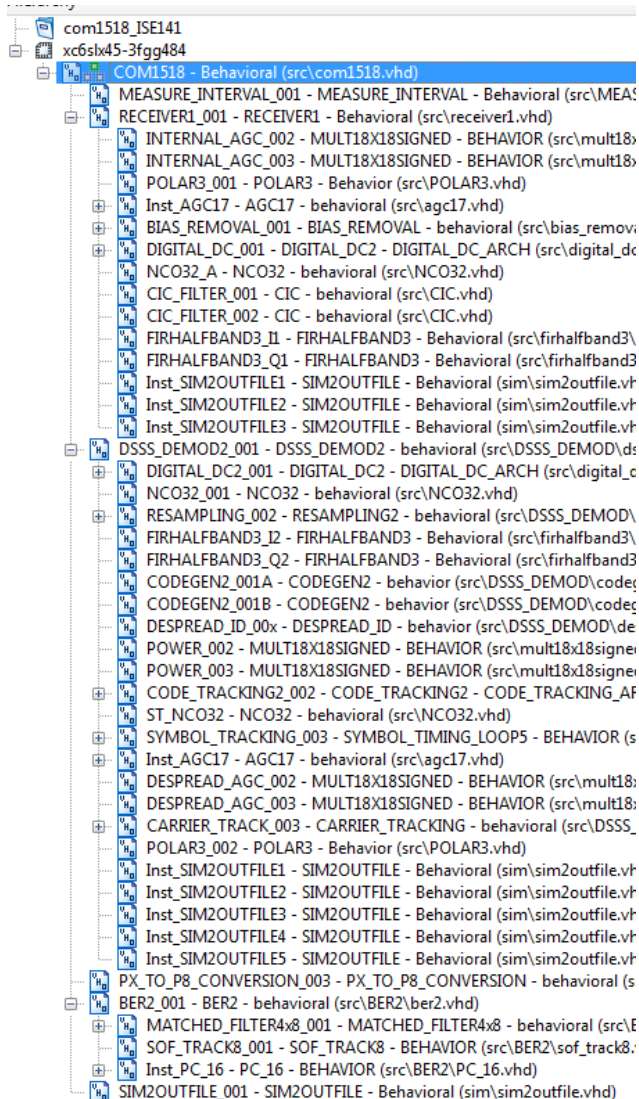
The entire project fits within a Xilinx Spartan-6 LX45. Therefore, the ISE project can be processed using the free Xilinx WebPack tools.

Xilinx-specific code

The VHDL source code was written in generic VHDL with few low-level Xilinx primitives. No Xilinx CORE is used. The Xilinx primitives are:

- RAMB16_Sx_Sx

VHDL software hierarchy



The code is stored with one, and only one, entity per file as shown above.

Comparison with Previous Version

Key Improvements with respect to COM-1418 Direct-Sequence Spread-Spectrum Demodulator

- 2x faster: maximum chip rate is $f_{clk}/2$
- Faster acquisition: parallel acquisition instead of sequential search.
- Symbol duration and alignment are independent of the spreading code period (2 independent tracking loops for code and symbol timing)
- Better performance through reduced dependencies between loops: code acquisition is less dependent on center frequency error.
- Independent AGCs before and after despreading.
- Phase ambiguity resolution under control of external FEC decoder.

ComBlock Ordering Information

COM-1518SOFT DSSS DEMODULATOR

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